

# **Models of financial markets with asymmetric information: additional utility and entropy**

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# 1 The model

(J. Amendinger, P.I., M. Schweizer, SPA '98; P.I., M. Pontier, F. Weisz, SPA '00; P.I. '01; J.-M. Corcuera, P.I., A. Kohatsu-Higa, D. Nualart '03; S. Ankirchner, P.I. '04; S. Ankirchner, S. Dereich, P.I. '04)

Financial market with  $d$  risky assets, time horizon 1; to simplify:  $d = 1$

## price process

$$\frac{dX_t}{X_t} = dW_t + \alpha_t dt, \quad W \text{ 1-dim. Wiener}$$

$$\mathbb{F} = (\mathcal{F}_t)_{0 \leq t \leq 1}, \quad \mathcal{F}_t = \sigma(W_s : s \leq t), \quad \alpha \text{ } \mathbb{F} \text{ - adapted}$$

## 2 information levels

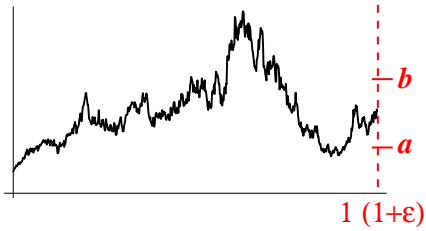
$$\begin{array}{ll} \text{regular trader} & \mathbb{F} = (\mathcal{F}_t)_{0 \leq t \leq 1} \\ \text{insider} & \mathbb{G} = (\mathcal{G}_t)_{0 \leq t \leq 1} \end{array}$$

$$\mathcal{G}_t = \mathcal{F}_t \vee \sigma(G),$$

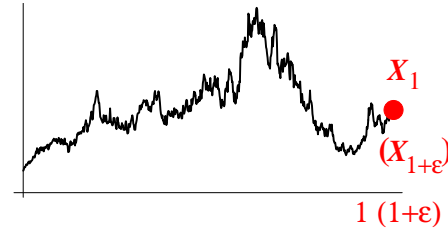
$G$   $\mathcal{F}_1$ -measurable r.v., *additional information*

(Lit: F. Baudoin, L. Denis, A. Grorud, M. Jeanblanc, J. Karatzas, I. Pikovsky, . . .)

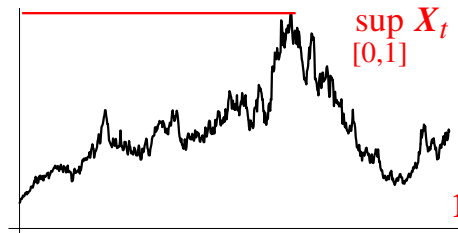
## 2 Examples



price interval at time  $1(1 + \epsilon)$



price of asset at time  $1(1 + \epsilon)$



maximal price before time 1



last passage of level  $a$  before time 1

## 3 expected utility

### development of portfolio

$$V_0 = 1, \quad \frac{dV_t}{V_t} = \frac{\pi_t}{\pi_t} \frac{dX_t}{X_t},$$

where

$$\begin{array}{l} \pi_{\mathbb{F}} - \text{adapted,} \\ \pi_{\mathbb{G}} - \text{adapted,} \end{array} \quad \int_0^1 \pi_s^2 ds < \infty \quad P - a.s.$$

### utility function

$$\text{logarithmic utility} \quad U(x) = \ln(x), \quad x > 0$$

**Pb:** compute *expected additional utility*

$$\begin{array}{ll} \text{regular trader:} & N_{\mathbb{F}} = \max_{\pi_{\mathbb{F}}\text{-portfolio}} E(\ln V_1) \\ \text{insider:} & N_{\mathbb{G}} = \max_{\pi_{\mathbb{G}}\text{-portfolio}} E(\ln V_1) \end{array}$$

$$\Delta N = N_{\mathbb{G}} - N_{\mathbb{F}}$$

### 3 utility increment: $N_{\mathbb{F}}$

$$dV_t = V_t \cdot \frac{\pi_t}{\pi_t} [dW_t + \alpha_t dt]$$

$$\implies V_t = \exp\left[\int_0^t \frac{\pi_s}{\pi_s} \alpha_s ds + \int_0^t \frac{\pi_s}{\pi_s} dW_s - \frac{1}{2} \int_0^t \frac{\pi_s^2}{\pi_s^2} ds\right]$$

$$\implies N_{\mathbb{F}} = \max_{\pi_{\mathbb{F}\text{-portfolio}}} E\left[\int_0^1 \pi_s \alpha_s ds - \frac{1}{2} \int_0^1 \pi_s^2 ds\right]$$

$$= \frac{1}{2} E\left(\int_0^1 \alpha_s^2 ds\right)$$

argument same as for maximizing

$$T : \mathbb{R} \ni \pi \mapsto \alpha\pi - \frac{1}{2}\pi^2, \quad \alpha \in \mathbb{R}$$

$$T'(\pi) = \alpha - \pi = 0$$

for  $\alpha = \pi$

### 3 utility increment: $N_G$

Pb when calculating  $N_G$ :

$$\int_0^\cdot \pi_s dW_s \text{ is no martingale !}$$

Basic problem of *grossissement de filtrations*:

$W$  in  $\mathbb{G}$  semimartingale?

$$\begin{array}{l} W \\ \mathbb{F} - \text{martingale} \end{array} = \begin{array}{l} \tilde{W} \\ \mathbb{F} - \text{martingale} \end{array} + \int_0^\cdot \mu_s^G ds$$

*information drift*

$$\implies N_G = \frac{1}{2} E \left( \int_0^1 [\alpha_s + \mu_s^G]^2 ds \right)$$

$$\begin{aligned} \Delta N &= N_G - N_F \\ &= \frac{1}{2} E \left( \int_0^1 (\mu_s^G)^2 ds \right) \end{aligned}$$

$$\left[ E \left( \int_0^1 \alpha_s \mu_s^G ds \right) = E \left( \int_0^1 \alpha_s [dW_s - d\tilde{W}_s] \right) = 0 \right]$$

## 4 The information drift as a function of $G$

(H. Föllmer, P.I. '94; Jacod '85; Yor, Jeulin '81-'85)

**Pb:** description of  $\mu^G$

$$\begin{aligned} \tilde{W} = W - \int_0^\cdot \mu_u^G du & \quad \mathbb{G}\text{-martingale} \\ \iff \\ E([W_t - W_s] 1_A 1_C(G)) & = E\left(\int_s^t \mu_s^G du 1_A 1_C(G)\right), \end{aligned}$$

$0 \leq s < t \leq 1, A \in \mathcal{F}_s, C \text{ Borel.}$

### Condition

$$(H) \quad P^G \text{ equivalent } P_t^G(\omega, \cdot) \quad P\text{-a.e. } \omega,$$

law of  $G$

cond. law of  $G$  given  $\mathcal{F}_t$

$$p_t(\cdot, l) = \frac{dP_t(\cdot, \cdot)}{dP^G}(l)$$

## 4 calculation of information drift $\mu^G$

simplify:  $A = \Omega$

$$\begin{aligned}
 E([W_t - W_s]1_C(G)) &= E(\int_s^t \mu_u^G du 1_C(G)) \\
 &= E(\int_C [W_t - W_s] P_t^G(\cdot, dl)) \\
 &= \int_C E([W_t - W_s] \cdot (p_t - p_s)(\cdot, l)) P^G(dl)
 \end{aligned}$$

$$p_t(\cdot, l) \mathbb{F} - \text{martingale}, \quad p_t(\cdot, l) = \int_0^t k_s^l dW_s$$

$$\begin{aligned}
 \implies & E([W_t - W_s] \cdot (p_t - p_s)(\cdot, l)) \\
 &= E\left(\int_s^t k_u^l du\right) \\
 &= E\left(\int_s^t \frac{k_u^l}{p_u(\cdot, l)} du \cdot p_t(\cdot, l)\right)
 \end{aligned}$$

$$\begin{aligned}
 \implies \mu_t^l &= \frac{k_u^l}{p_u(\cdot, l)} = \frac{\frac{d}{dt} \langle p(\cdot, l), W \rangle_t}{p_t(\cdot, l)} \\
 \mu^G &= \mu^l|_{l=G}
 \end{aligned}$$



## 5 Examples

**Example 1:**  $G = W_{1+\epsilon}$  ( $\epsilon \geq 0$ )

$A$  Borel; then

$$\begin{aligned} P(W_{1+\epsilon} \in A | \mathcal{F}_t) &= P(W_{1+\epsilon} - W_t \in A - W_t) \\ &= N(0, 1 + \epsilon - t)(A - W_t) \end{aligned}$$

$\implies$  **(H)**

**Example 2:**  $G = \sup_{0 \leq t \leq 1} W_t$ ,  $G_t = \sup_{0 \leq s \leq t} W_s$

$$G = G_t \vee (W_t + \sup_{t \leq s \leq 1} (W_s - W_t)) =: \tilde{G}_{1-t}$$

$$\implies P_t^G = F_{1-t}(G_t - W_t) \cdot \delta_{G_t} + \dots$$

distribution function of  $\tilde{G}_{1-t}$

$\implies$  **(H)** not valid

Amendinger (thesis):

**(H)**  $\implies$  **(NFLVR)**  $\implies$  **no arbitrage for insider**

## 6 Extension of Jacod's framework

Need new interpretation of  $\mu_t^G = \frac{k_u^l}{p_u(\cdot, l)} = \frac{\frac{d}{dt} \langle p(\cdot, l), W \rangle_t}{p_t(\cdot, l)} \Big|_{l=G}!$

### a) Malliavin's calculus

$$p_t(\cdot, l) = \int_0^t k_u^l dW_u = \int_0^t D_s p_s(\cdot, l) dW_s$$

Clark-Ocone

$$\implies \frac{d}{dt} \langle P(\cdot, l), W \rangle_t = D_t p_t(\cdot, l)$$

$$\implies \mu_t^G = D_t \ln p_t(\cdot, l) \Big|_{l=G}$$

### b) R-N derivatives

$$\frac{D_t p_t(\cdot, l)}{p_t(\cdot, l)} = \frac{D_t \frac{dP_t^G}{dPG}(l)}{\frac{dP_t^G}{dPG}(l)} \quad (\text{assume } D_t \leftrightarrow \frac{d}{dPG})$$

$$= \frac{D_t P_t^G(\cdot, dl)}{P_t^G(\cdot, dl)}(l)$$

Needs Malliavin calculus for **measure valued objects!** (P.I., M. Pontier, F. Weisz)

Replace **(H)** with

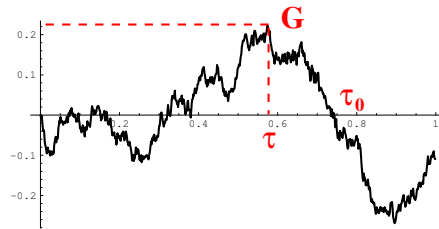
$$\text{(AC)} \quad D_t P_t^G(\cdot, dl) \ll P_t^G(\cdot, dl)!$$

# 7 Examples

Back to Example 2:  $G = \sup_{0 \leq t \leq 1} W_t$

$$P_t^G = F_{1-t}(G_t - W_t) \cdot \delta_{G_t} + \dots$$

$$\begin{aligned} \Rightarrow \mu_t^G &= - \frac{f_{1-t}(G_t - W_t)}{F_{1-t}(G_t - W_t)} \Big|_{G_t=G} + \dots \\ &\approx - \frac{1}{G - W_t} \quad \text{near } \tau \end{aligned}$$



excursion theory  $\Rightarrow (G - W_t : \tau \leq t \leq \tau_0)$  is **BES(3)**

trajectorial properties of BES(3)  $\Rightarrow$

$$\begin{aligned} \int_0^1 |\mu_s^G| ds &< \infty \quad P - \text{a.s.} \\ \int_0^1 (\mu_s^G)^2 ds &= \infty \quad \text{on a set of positive probability} \end{aligned}$$

$\Rightarrow W$  semimartingale in  $\mathbb{G}$ ; no equivalent martingale measure w.r.t.  $\mathbb{G}$ ; arbitrage!

## 8 structure of information drift, general enlargement

**Pb:**  $S = M + \alpha \cdot \langle M, M \rangle$  w.r.t.  $\mathbb{G}$ , structure of  $\alpha$ ?

**Hypothesis:**  $\Omega$  standard Borel  $\implies \mathcal{G}_t$  countably generated, regular cond. probabilities exist

reg. cond. prob. of  $\mathcal{F}$  given  $\mathcal{F}_t : P_t(\cdot, \cdot)$

$$P_t(\cdot, A) = P(A) + \int_0^t k_s(\cdot, A) dM_s + L_t^A, \quad L^A \text{ orthogonal to } M$$

(ACL)  $k_t(\cdot, \cdot)$  signed measure,

$$k_t(\omega, \cdot) \Big|_{\mathcal{G}_{t-}} \ll P_t(\omega, \cdot) \Big|_{\mathcal{G}_{t-}}$$

$$\gamma_t(\omega, \omega') = \frac{dk_t(\omega, \cdot)}{dP_t(\omega, \cdot)} \Big|_{\mathcal{G}_{t-}}$$

**Thm 2:** (ACL)  $\implies \alpha_t(\omega) = \gamma_t(\omega, \omega)$  gives information drift of  $\mathbb{G}$  relative to  $\mathbb{F}$ .

**Pb:** under which conditions is (ACL) satisfied?

## 8 structure of information drift ( $L = 0$ )

Crucial observation:  $0 \leq s < t$ ,  $\mathcal{P} = \{A_1, \dots, A_n\}$  partition of  $\Omega$  in  $\mathcal{G}_s$ , Itô's formula:

$$\begin{aligned}
 (*) & \sum_{k=1}^n [1_{A_k} \ln P_s(\cdot, A_k) - 1_{A_k} \ln P_t(\cdot, A_k)] \\
 = & \sum_{k=1}^n \left[ - \int_s^t \frac{1}{P_u(\cdot, A_k)} 1_{A_k} dP_u(\cdot, A_k) + \int_s^t \frac{1}{2} \frac{1}{P_u(\cdot, A_k)^2} 1_{A_k} d\langle P(\cdot, A_k), P(\cdot, A_k) \rangle_u \right] \\
 = & \mathbb{G} - \text{mart.} + \sum_{k=1}^n \int_s^t \left[ -\frac{k_u}{P_u}(\cdot, A_k) \alpha_u + \frac{1}{2} \left(\frac{k_u}{P_u}\right)^2(\cdot, A_k) \right] 1_{A_k} d\langle M, M \rangle_u
 \end{aligned}$$

Jensen, Cauchy-Schwarz:  $\frac{1}{2} E \int_s^t \sum_{k=1}^n \left(\frac{k_u}{P_u}\right)^2(\cdot, A_k) 1_{A_k} d\langle M, M \rangle_u$

$$\leq E \left( \int_s^t \sum_{k=1}^n \left(\frac{k_u}{P_u}\right)^2(\cdot, A_k) 1_{A_k} d\langle M, M \rangle_u \right)^{\frac{1}{2}} E \left( \int_s^t \alpha_u^2 d\langle M, M \rangle_u \right)^{\frac{1}{2}}$$

$\Rightarrow$

$$E \int_s^t \sum_{k=1}^n \left(\frac{k_u}{P_u}\right)^2(\cdot, A_k) 1_{A_k} d\langle M, M \rangle_u \leq 4E \left( \int_s^t \alpha_u^2 d\langle M, M \rangle_u \right).$$

## 8 structure of information drift, general enlargement

Apply martingale convergence along nested sequence of partitions in  $\mathcal{G}_s$ , let  $s \uparrow t$ :

**Thm 3:**  $\mathcal{G}_{t-} \rightarrow \mathbb{R}, A \mapsto k_t(\cdot, A)$  can be chosen as signed random measure, (ACL) satisfied.

Summary:

**Thm 4:** Equivalent:

i)  $k_t(\omega, \cdot)$  signed measure,

$$k_t(\omega, \cdot) \Big|_{\mathcal{G}_{t-}} \ll P_t(\omega, \cdot) \Big|_{\mathcal{G}_{t-}} \quad \text{for } P_M = P \otimes \langle M, M \rangle\text{-a.e.}(\omega, t),$$

R-N process

$$\gamma_t(\omega, \omega') = \frac{dk_t(\omega, \cdot)}{dP_t(\omega, \cdot)} \Big|_{\mathcal{G}_{t-}} \quad \text{square integrable on diagonal } \omega = \omega' \text{ for } P_M$$

ii)  $M$  is  $\mathbb{G}$ -semimartingale; Doob-Meyer decomposition

$$M = \tilde{M} - \alpha \cdot \langle M, M \rangle, \quad \alpha \text{ square integrable for } P_M$$

In this case:

$$\alpha_t(\omega) = \gamma_t(\omega, \omega), \quad \text{for } P_M \text{-a.e. } (\omega, t).$$

## 9 Relationship with entropy: initial enlargement

$$p_t(\cdot, l) = \int_0^t k_u^l dW_u \quad \mathbb{F} - \text{martingale};$$

Itô's formula  $\implies$

$$\ln p_t(\cdot, l) = \int_0^t \frac{1}{p_u(\cdot, l)} k_u^l dW_u - \frac{1}{2} \int_0^t (\mu_u^l)^2 du$$

**Thm 6:** **(H)**  $\implies \frac{1}{p_t(\cdot, G)}$   $\mathbb{G}$ -martingale

$\implies$  (analogously)

**Thm 7:**  $\Delta N = \frac{1}{2} E(\int_0^1 (\mu_s^G)^2 ds) = E(\ln p_1(\cdot, G))$

*additional log utility = entropy of additional information*

## 10 explicit results under (H)

**Case 1:**  $G$  discrete

$$p_i = P(G = x_i), \quad i \in \mathbb{N}, \quad \sum_{i \in \mathbb{N}} p_i = 1$$

$$p_t(\cdot, G) = \sum_{i \in \mathbb{N}} \frac{P(G = x_i | \mathcal{F}_t)}{p_i} 1_{\{G=x_i\}}$$

$$E(\ln p_1(\cdot, G)) = \sum_{i \in \mathbb{N}} p_i \ln \frac{1}{p_i}$$

**Thm 8:**  $G$  discrete; then  $\Delta N < \infty \iff$  entropy of  $G$  finite

**Case 2:**  $G$  not purely atomic

there is a Borel set  $B$  with  $c = P^G(B) > 0$ , and for each  $n \in \mathbb{N}$  a partition  $(B_i^n)_{1 \leq i \leq n}$  with  $P^G(B_i^n) = \frac{c}{n}$

$$G_n = \sum_{i=1}^n i 1_{B_i^n}(G) \implies$$

$$\begin{aligned} \text{entropy of } G &\geq \text{entropy of } G_n \\ E(\ln p_1(\cdot, G)) &\geq \sum_{i=1}^n \ln\left(\frac{n}{c}\right) \cdot \frac{c}{n} \rightarrow \infty \end{aligned}$$

**Thm 9:**  $G$  not purely atomic  $\implies \Delta N = \infty$ .



# 11 Examples

**Example 3:**  $\mathbb{R} \ni a < b \in \mathbb{R}; G = 1_{[a,b]}(W_1)$

$$\begin{aligned} p_1 &= P(W_1 \in [a, b]) \\ p_2 &= 1 - p_1 \\ \implies \Delta N &= p_1 \ln \frac{1}{p_1} + p_2 \ln \frac{1}{p_2} \end{aligned}$$

**Example 4:**  $G = W_{1+\epsilon} \quad (\epsilon > 0)$

$$\implies (H), (NFLVR), \Delta N \rightarrow \infty \quad \text{as } \epsilon \rightarrow 0$$

**Example 5:** (P.I. '01)

progressive enlargement by  $\tau_a$ , the last passage time through level  $a$  by Wiener process or regular diffusion

$\implies$  arbitrage

# 12 Utility increment in general enlargement

(S. Ankirchner, P.I. '03; S. Ankirchner, S. Dereich, P.I. '04)

**General setting:** price process  $S$  adapted w.r.t.  $\mathbb{F} = (\mathcal{F}_t)_{0 \leq t \leq 1}$ ,  $\mathbb{G} = (\mathcal{G}_t)_{0 \leq t \leq 1}$ ,

$$\mathcal{F}_t \subset \mathcal{G}_t$$

**agent's** information horizon  $\mathbb{G}$ ,  $S = M + \alpha \cdot \langle M, M \rangle$ ,  $M$  continuous,  $\theta$   $x$ -admissible for  $x > 0$  if  $\mathbb{G}$ -predictable,  $S$ -integrable,  $x + (\theta \cdot S)_t > 0$

$$u_{\mathbb{G}}(x) = \sup_{\theta \text{ } x\text{-admissible}} E(\log(x + (\theta \cdot S)_T)) = \ln x + \frac{1}{2} E\left(\int_0^1 \alpha_s^2 d\langle M, M \rangle_s\right)$$

$\mathbb{G} = (\mathcal{G}_t)_{0 \leq t \leq 1}$ ,  $\mathbb{H} = (\mathcal{H}_t)_{0 \leq t \leq 1}$  finite utility filtrations,  $\mathcal{G}_t \subset \mathcal{H}_t$

$\mathbb{G}$ :  $S = M + \alpha \cdot \langle M, M \rangle$        $\mathbb{H}$ :  $S = N + \beta \cdot \langle M, M \rangle$

information drift  $\mathbb{G} \rightarrow \mathbb{H}$   $\mu = \beta - \alpha$

$$E\left(\int_0^1 \alpha(\beta - \alpha) d\langle M, M \rangle\right) = E\left(\int_0^1 \alpha(d(N - M))\right) = 0$$

**Thm 1:**  $u_{\mathbb{H}}(x) - u_{\mathbb{G}}(x) = \frac{1}{2} E\left(\int_0^1 \mu^2 d\langle M, M \rangle\right)$

# 13 additional utility and entropy

$\mathcal{G}$  sub- $\sigma$ -algebra of  $\mathcal{F}$ ,  $R, Q$  probability measures on  $\mathcal{F}$ ;

*relative entropy* of  $R$  with respect to  $Q$  on  $\mathcal{G}$ :

$$\mathcal{H}_{\mathcal{G}}(R\|Q) = \begin{cases} \int \log \frac{dR}{dQ} \Big|_{\mathcal{G}} dR, & \text{if } R \ll Q \\ \infty, & \text{else.} \end{cases}$$

*additional information* of  $\mathcal{G}$  relative to  $(\mathcal{F}_r)$  on  $[s, t]$  ( $0 \leq s < t \leq T$ ):

$$H_{\mathcal{G}}(s, t) = \int \mathcal{H}_{\mathcal{G}}(P_t(\omega, \cdot) \| P_s(\omega, \cdot)) dP(\omega).$$

$\mathbb{G}$  enlargement of  $\mathbb{F}$ , information drift  $\mu$ ,  $\Delta_n = \{0 = t_0^n < \dots < t_{k_n}^n = 1\}$ ,  $n \in \mathbb{N}$ , sequence of partitions of  $[0, 1]$ , mesh  $|\Delta_n| \rightarrow 0$

**consequence of (\*):**

**Thm 5:**

$$H_{\mathbb{G}|\mathbb{F}} = \lim_{n \rightarrow \infty} H_{\Delta_n} = \sum_{i=0}^{n-1} H_{\mathcal{G}_{t_i^n}}(t_i^n, t_{i+1}^n) = \frac{1}{2} E \int_0^1 \mu_u^2 d\langle M, M \rangle_u.$$

*additional log utility = additional information*

# 14 imperfect dynamical information

(J.M. Corcuera, P.I., A. Kohatsu-Higa, D. Nualart '02)

**Example 6:**  $G = W_1$

Thm 9  $\implies \Delta N = \infty$ , arbitrage

**Pb:** can additional noise on  $G$  make  $\Delta N < \infty$ ?

**Example 7:**  $L_t = W_1 + \tilde{W}_{g(1-t)}$ ,  $\tilde{W}$  independent of  $W$

$$\mathcal{G}_t = \mathcal{F}_t \vee \sigma(L_s : s \leq t)$$

**Thm 10:**  $g(t) = Kt^p$ ;

$$\begin{aligned} p < 1 &\implies \Delta N < \infty, \\ p \geq 1 &\implies \Delta N = \infty. \end{aligned}$$